



Matrice 200 Series Release Notes

Date:	2018.06.20
Aircraft Firmware:	V01.01.0911
Remote Controller Firmware:	V01.01.0002
DJI GO 4 app:	iOS V 4.2.16, Android V 4.2.16
DJI Pilot app :	Android V 0.6.1
CrystalSky Firmware:	V2.6.6.0

What's New?

- Fixed a bug where more or less photos are captured when both cameras simultaneously took photos in the dual downward gimbal configuration. (If Zenmuse XT is used, please attach the Zenmuse XT with the XT Adapter together to the Gimbal Connector I, and use the DJI Assistant 2 for Matrice software to update the XT Adapter.)
- Optimized the Unlocking feature for GEO System.
- Improved the return to home and landing accuracy of the M210 RTK.
- Fixed a bug where prompts failed for flight limits and unlocking.
- Fixed a rare bug where “IMU abnormality, please calibrate the IMU” appears during turbulent flight.
- Fixed a bug where aircraft and gimbal problems happened when the X4S\X5S yaw rotation is reversed with the aircraft. Note that the X4S\X5S should be attached to the Gimbal Connector I when updating.
- Fixed a bug where the aircraft distance incorrectly displayed in app when exiting flight from the simulator.
- Fixed and optimized other issues.

Notes:

- The Zenmuse Z30 should be updated to v01.00.00.47 before using the gimbal with this firmware. Reset the gimbal parameters after the Zenmuse Z30 firmware update is complete.
- Only newer Zenmuse XT models are compatible with the Matrice 200. A replacement may be required if your XT model isn't supported. Please contact DJI Support to learn more about various XT model compatibility. The Zenmuse XT gimbal adapter and DJI Pilot app are also required when used with the Matrice 200.
- If the firmware update fails, restart the aircraft and DJI Pilot \ DJI GO 4, then try updating again.